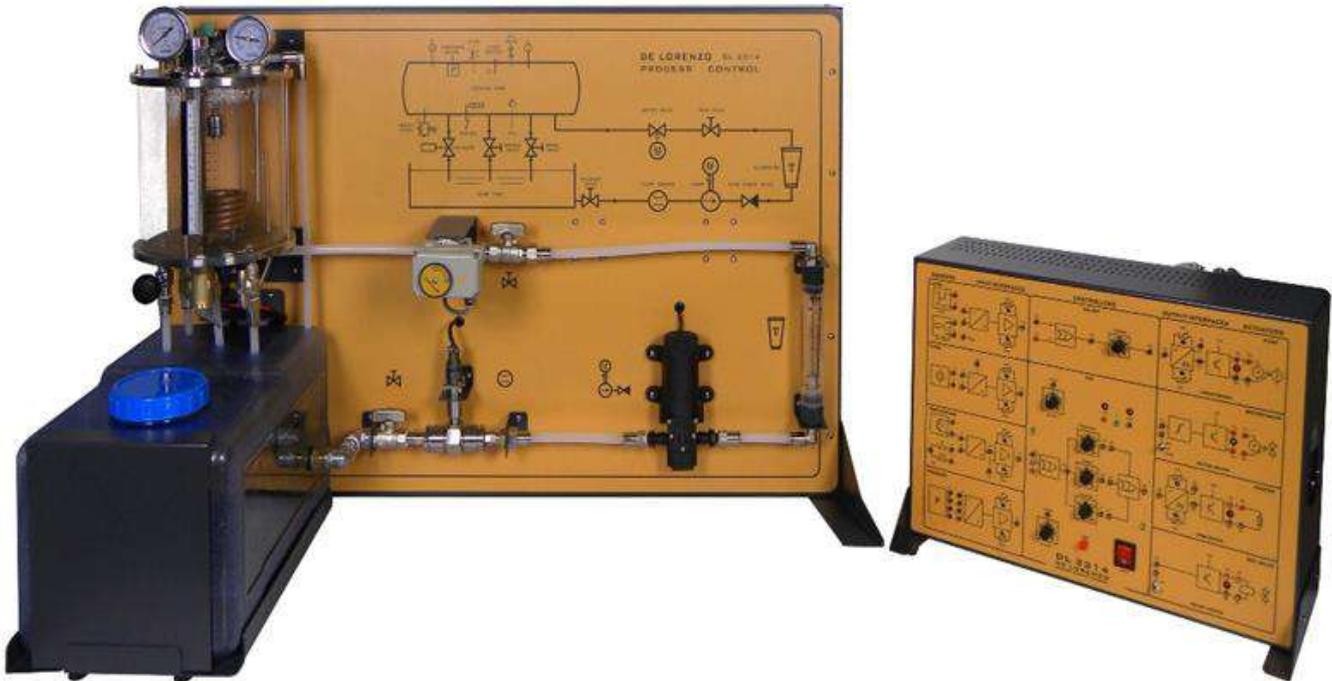




## PROCESS CONTROL TRAINER DL 2314



### Product overview

Bench for the study of process control field. It includes valves, pump, tanks, sensors, and drivers. It consists of an experiment module (process panel), a control module with built-in power supply (control panel).

With this trainer, the students will be guided step by step into the following experiments; how to calibrate a sensor, how to obtain the characteristic of a static process and time constant, how to control a process by ON-OFF, Proportional, Proportional-Integral, Proportional derivative, Proportional-Integral-Derivative.

#### **Ideal for 4 students to work simultaneously.**

Vocational and technical schools.

Applicable to courses in: **Automation, Sensors and Actuators, PID, Process Control.**

### Highlights

- The trainer allows a training flexibility for in all process automation topics and it is composed three different section: **PROCESS PANEL, CONTROL PANEL**
- With the detailed educational manual, the students will be guided step by step into learning: how to calibrate the sensors, how to control a process by ON-OFF system and Proportional-Integral-Derivative system.
- Each experiment, described in detail in the educational manual, is related with real industrial applications.
- The modular trainer offers all modules and components required for basic-to-advanced instruction in processes control and automation.
- it is possible to connect to the trainer a personal computer with suitable interface module and software (PC with **DL 1893** and **DL 2314SW**)



## LIST OF EXPERIMENTS

- Level sensor settings
- Characteristics of the motor of the pump
- Characteristics of the pump
- Characteristics of the static process
- Time constant of the process
- ON - OFF control of the level
- ON - OFF control of the level with "Sol Valve"
- ON - OFF control of the level with "Float Switch"
- Closed loop Proportional control of the level
- Closed loop Proportional-Integral control of the level
- Closed loop Proportional-Derivative control of the level
- Closed loop Proportional-Integral-Derivative control of the level
- Flow sensor
- Closed loop Proportional control of the flow
- Closed loop Proportional-Integral control of the flow
- Closed loop Proportional-Derivative control of the flow
- Closed loop Proportional-Integral-Derivative control of flow
- Temperature sensor
- Measurement of the characteristics of the heating
- Closed loop Proportional control of the temperature
- Closed loop Proportional-Integral control of the temperature
- Closed loop Proportional-Derivative control of the temperature
- Closed loop Proportional-Integral-Derivative control of the temperature
- Pressure sensor
- Pressure sensor as a level sensor
- ON - OFF control of the level through the pressure sensor



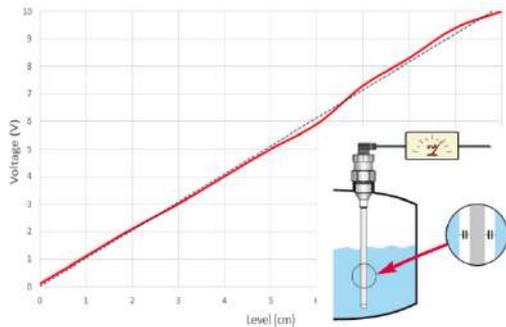
## TECHNICAL SPECIFICATIONS

The AUTOMATIC PROCESS CONTROL trainer allows the study and performing of experiments in the field of process control.

- Power supply: single-phase from mains
- **Process Control Trainer/Process panel**, including:
  - Water tank capacity: 20 litres approx.
  - Motor recirculation pump: 6 litres/minute
  - Motor valve: electro modulated valve used for controlling the water flow
  - Motor pump with thermal protection and flow check valve
  - Flow sensor: 8000 pulses/ litre
  - Pipelines (for processing water supply and for water draining out from the process tank)
  - Delivery valve (the main water supply valve)
  - Turbine Flow Meter (flow sensor with volumetric measuring turbine)
  - Visual Flowmeter (indicator for flow rate)
  - Manually valve (for reducing the water flow)
  - Pressurized vessel capacity: 5 litres approx., including:
    - Capacitive level sensor and a Metric scale for measuring the water level (cm or mm)
    - Float switch (to detect the level of water within the pressurized tank)
    - Heating element; Temperature sensor (PT100) and a Thermometer for measuring the temperature inside the process tank (°C or °F)
    - Pressure sensor and a Pressure gauge for measuring the pressure (bar or psi)
    - 4 types of Valves (3 manual and 1 controlled)
    - Safety valve
- **Process Control Trainer/Control panel**, including:
  - Input's interface (Sensors)
    - LEVEL transducer
    - FLOW transducer
    - TEMPERATURE transducer
    - PRESSURE transducer
  - Control's interface (Controllers)
    - ON – OFF
    - ON – OFF with hysteresis
    - PID (P, PI, PD, PID)
  - Output's interface (Actuators)
    - Linear driver for PUMP
    - Driver for MOTOR VALVE
    - PWM driver for HEATER
    - ON – OFF driver for SOL VALVE



## EXPERIMENT DESCRIPTION



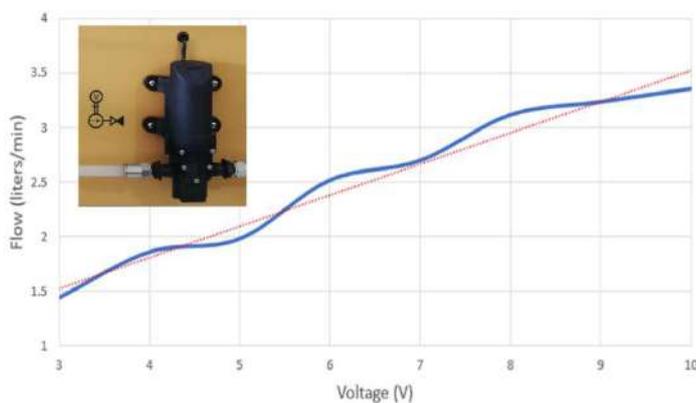
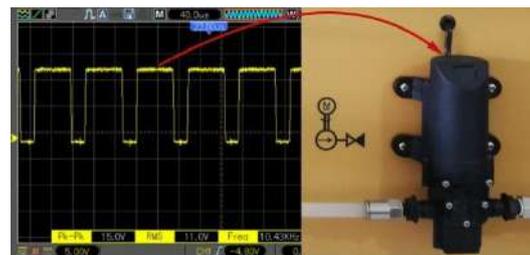
### **Level sensor settings**

From the beginning of the experiments, the students will learn about different types of sensors. They learn how to calibrate and use a capacitive fluid level sensor in order to measure the water level and to determine the sensor characteristics.

The level transducer (L/U) is used to calibrate the level sensor for a correspondence of 1 V to 1 cm.

### **Characteristics of the motor of the pump**

The experiment is very practical because they will learn what is the Control in PWM (Pulse Width Modulation) of a DC motor. Using a classical oscilloscope, the students will analyze the control signals of a pump motor. The reference input signal of the motor is a triangular 10Vpp while the duty cycle of PWM is modulated from the control panel of trainer.



### **Characteristics of the pump**

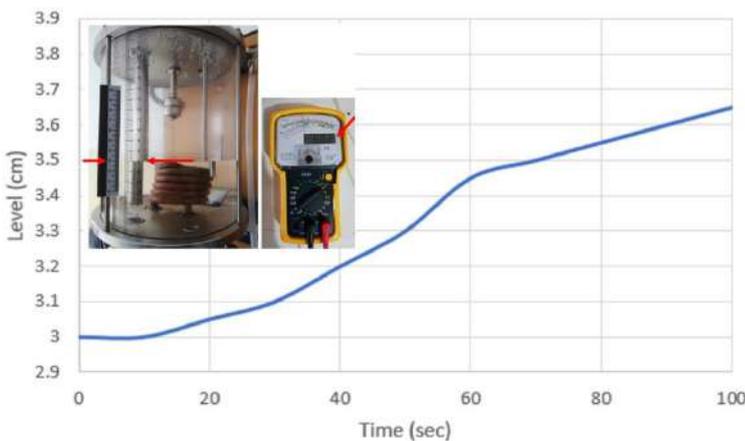
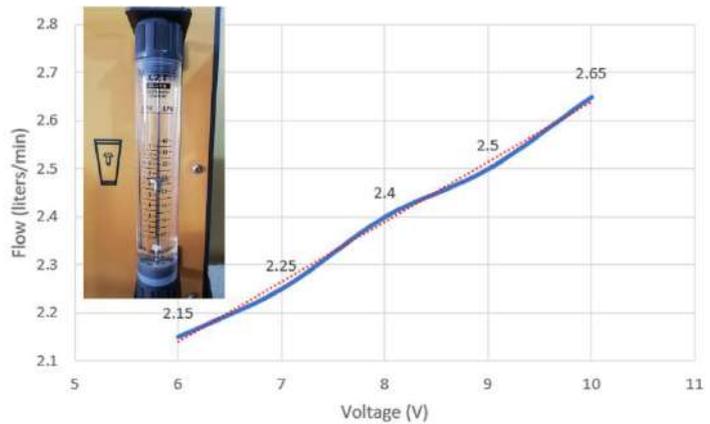
After running this experiment, the students will understand the working principle of a diaphragm pump. They will learn how to compute the flow and how to measure it using the flowmeter to draw the characteristic curve of pumps flow.



### Characteristics of the static process

Using the knowledge from the previous test, it will help to perform this test. The main objective is to understand how the flow will influence the rising time of the fluid level rate in a level control process.

The flow transducer (f/U) is used to calibrate the flow sensor for a correspondence of 1 V output is to 0.5 liters per minute.



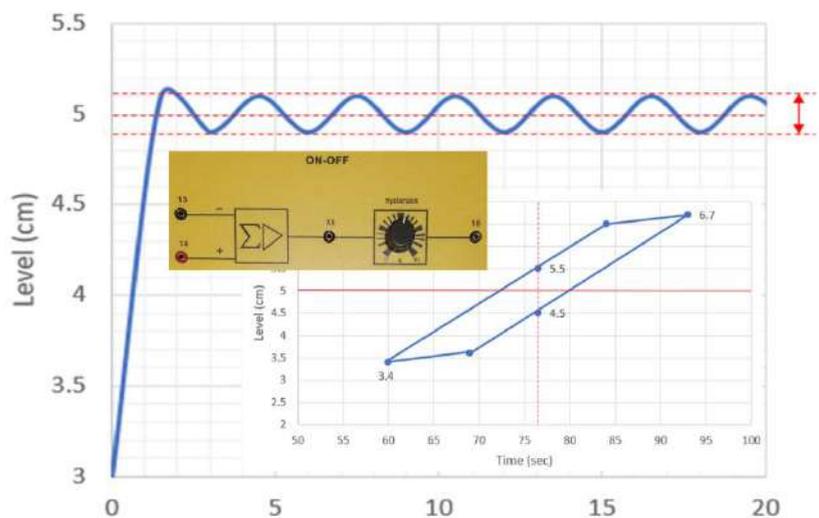
### Time constant of the process

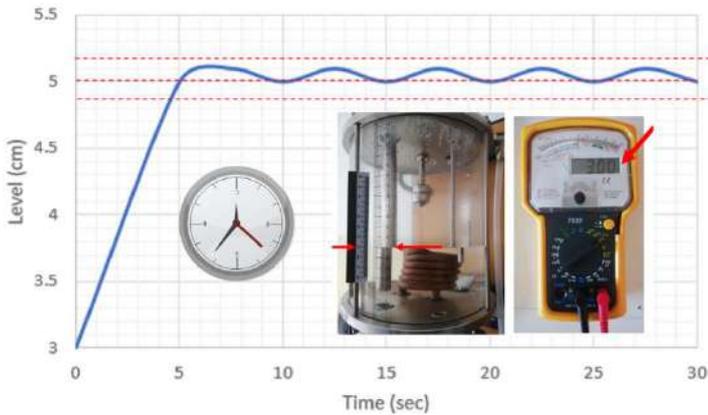
What is the time constant of a process? How do they calculate it? The students can answer this question by performing this experiment. The time constant estimation is made up of the water flow in the tank, as a ratio between the input flow and the draining flow rate. This process is an example of parameter identification.

### ON - OFF control of the level

What are the effects of the hysteresis on the level control? The students will find out while learning how to measure the dynamic response of the process. They will use the capacitive level sensor to measure the water level in the process tank.

This knowledge is very important because in practical situations, one of the most widely used types of control is the ON/OFF control.





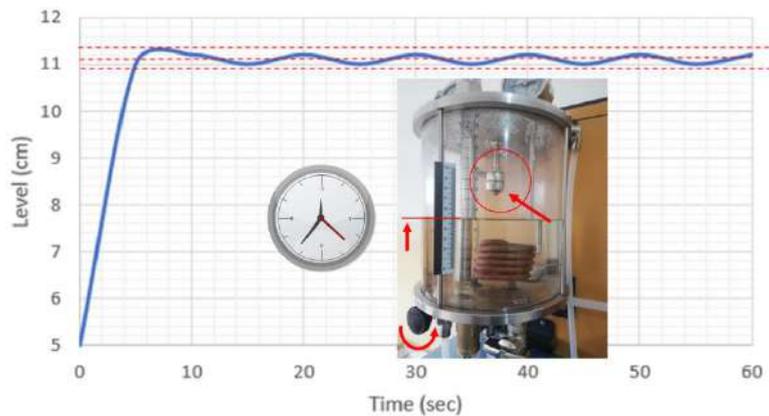
### **ON - OFF control of the level with "Sol Valve"**

In this experiment, the students will use their accumulated knowledge regarding the hysteresis on the level control. This will measure the upward and downward number of movements of the level between the "Start and Stop" of the electro-valve with a hysteresis of 0%, 15% and 30%.

### **ON - OFF control of the level with "Float Switch"**

Students will perform practical study to maintain a constant level in the tank using an "ON-OFF" level sensor and the electro sol valve.

They will learn how to measure the water level variation in time. To determine the hysteresis curve for "On - Off" control of the level, they use the engraved mobile scale or the level sensor and float switch.



### **Closed loop control of the LEVEL**

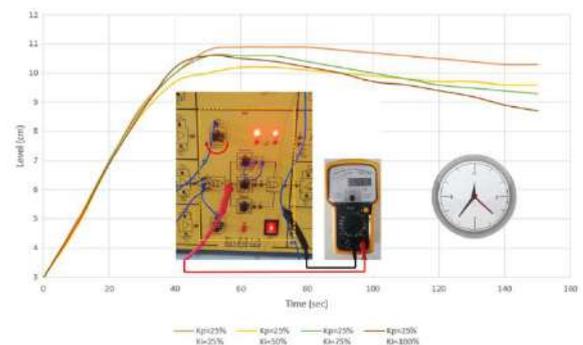
#### **Closed loop Proportional control of the level**

#### **Closed loop Proportional-Integral control of the level**

#### **Closed loop Proportional-Derivative control of the level**

#### **Closed loop Proportional-Integral-Derivative control of the level**

To be able to study the closed loop control, first they need to check the effects of the gain loop on the dynamic response of the system. It is very interesting to observe the output characteristic of the PID controller for different  $K_p$ ,  $K_d$  and  $K_i$  constant values. Ziegler-Nichols method is used in tuning of PID controller. The students learn how to determine the PID parameters to obtain the controlled level.





## Closed loop control of the FLOW

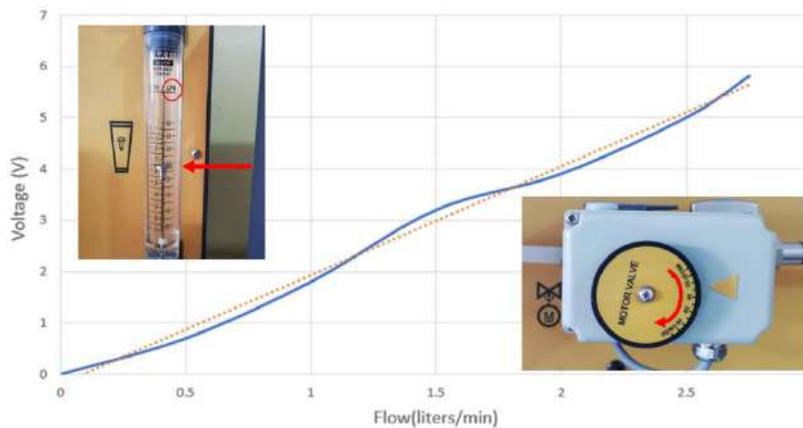
### Flow sensor

*Closed loop Proportional control of the flow*

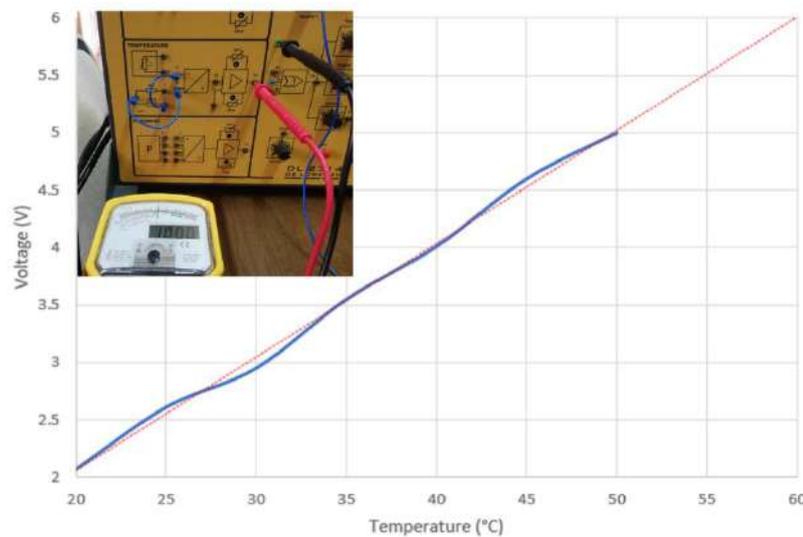
*Closed loop Proportional-Integral control of the flow*

*Closed loop Proportional-Derivative control of the flow*

*Closed loop Proportional-Integral-Derivative control of flow*



During these experiments, the students learn how to measure the water flow rate by using the engraved scale of the direct flow meter or the turbine flow sensor. After analyzing the results, they must be able to implement the tuning of the PID control of the system with optimum stability.



### Temperature sensor

The students learn how to measure the temperature variation in time, using the engraved thermometer scale or the temperature sensor, in order to determine and compute the characteristic curve of PT100 sensor (RDT).

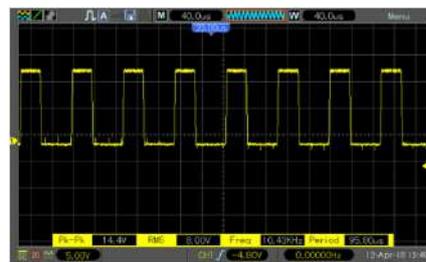
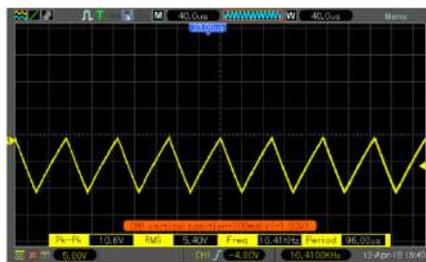
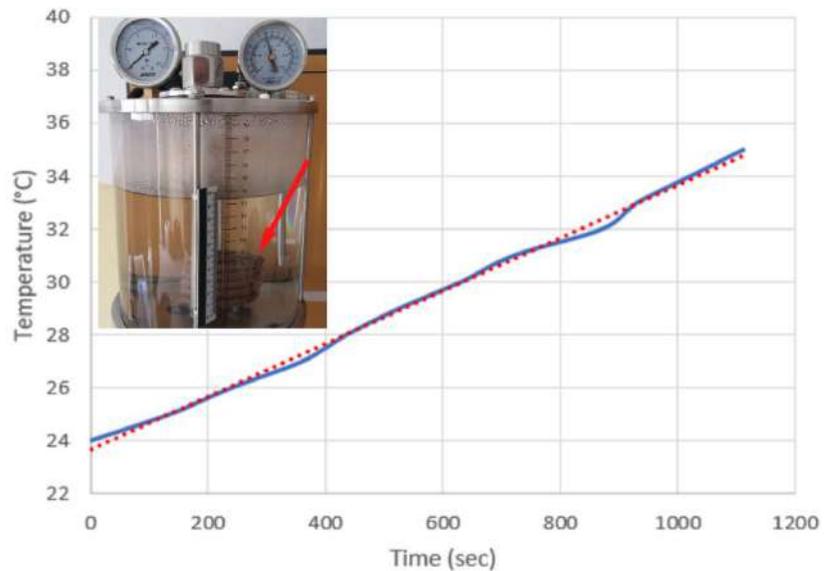
The temperature transducer ( $u/U$ ) is used to calibrate the temperature sensor for a correspondence of 1 V to 10 degrees Celsius.



## **Measurement of the characteristics of the heating**

This experiment is similar with the previous one, but this time the students will understand the working principle of a resistive temperature sensor to measure the temperature in the industrial process tank.

Using a classical oscilloscope, the students can analyze the waveform of the PWM for the heating element.



## **Closed loop control of the TEMPERATURE**

**Closed loop Proportional control of the temperature**

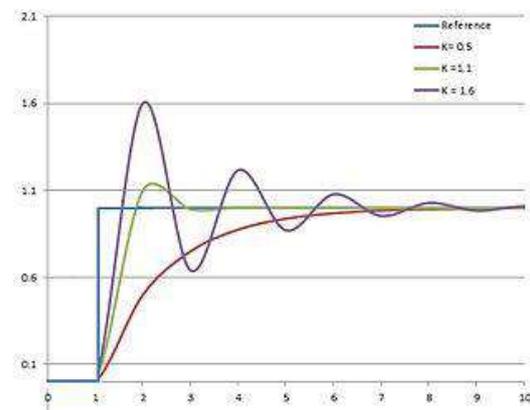
**Closed loop Proportional-Integral control of the temperature**

**Closed loop Proportional-Derivative control of the temperature**

**Closed loop Proportional-Integral-Derivative control of the temperature**

The students will learn that in a temperature controller system, the controller accepts a temperature sensor as an input, such as an RTD or thermocouple, and compares the actual temperature with the required control temperature or setpoint. The output is then provided to a control element.

After analyzing the results, they will be able to fine tune the PID control of the system.

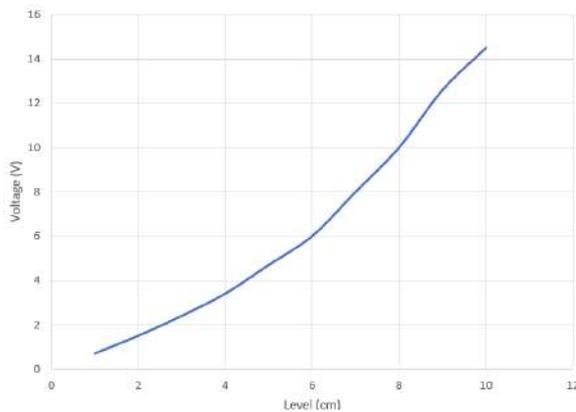
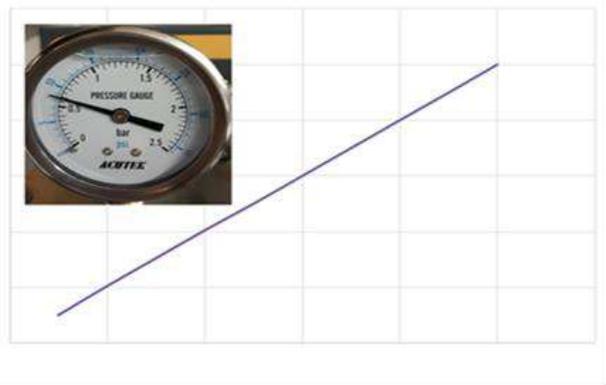




## **Pressure sensor**

The students will learn how to measure the pressure, using the electronic pressure sensor or pressure gauge scale, to determine and compute the characteristic curve of the pressure sensor.

The pressure transducer (P/U) is used to calibrate the pressure sensor for a correspondence of 1 V is 0.15 bar. The characteristics of a pressure transducer will be determined.



## **Pressure sensor as a level sensor**

The main objective of this experiment is measuring the pressure, using the electronic pressure sensor or pressure gauge scale, to determine the characteristic curve of the level vs. pressure response.

## **ON - OFF control of the level through the pressure sensor**

The students, already familiar with the procedure of "ON-OFF" control, will perform the operation of a closed loop "ON-OFF" control system using the pressure sensor as a level sensor.

The knowledge regarding the effects of the hysteresis on the control will be unused in controlling the pressure.

