

# SMARTSIM

DL SMART-DCS

DYNAMIC CONTROL  
SYSTEMS COURSE



DE LORENZO

# SMART SIMULATOR FOR LEARNING CONTROL WITH PLC

The DL SMART-DCS is a software that has been developed to teach dynamic control with PLC in a unique and effective way.

With this software, students can improve their individual experience on studying control systems in practice.

Professors can explore this trainer to provide experiments to students with the following topics:

-  **Control systems: Introduction, examples, block diagrams, open and close loop systems;**
-  **Control principles: Mathematical modeling of dynamic systems, linearity, transfer function, block diagrams, frequency response, stability, computational simulation;**
-  **Control approaches: Classic, optimal, fuzzy, other approaches;**
-  **ON-OFF and PID Control (P, PI, D, PID): Designing and tuning by analytic and experimental methods, and study of the P, D and I control actions;**
-  **Analysis of systems of first, second and third order in transitory and steady state.**

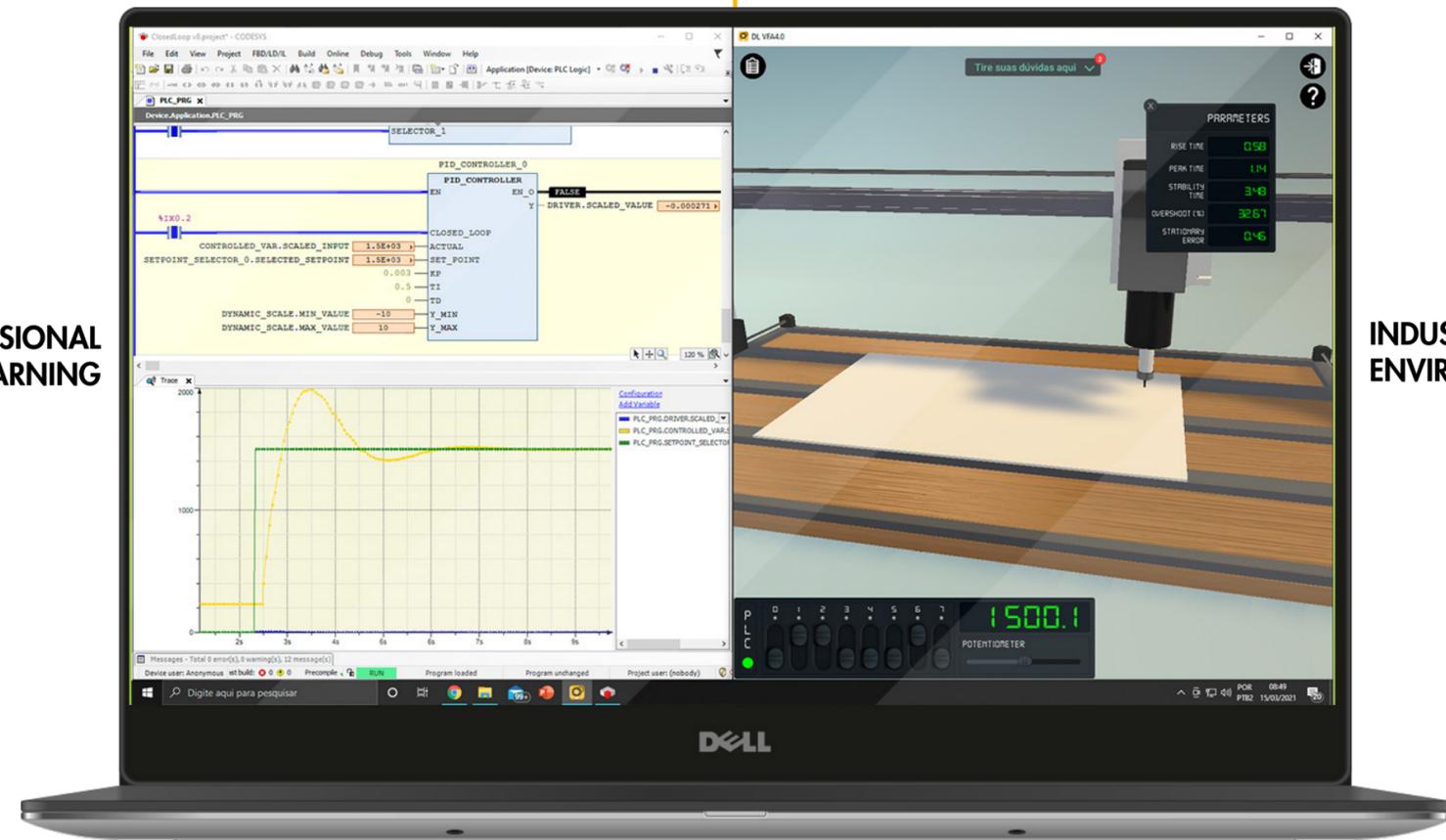
This software works integrated to a softPLC (not included) which can be: The Siemens PLCSIM or Codesys Control.

**INDUSTRIAL  
PLC PROGRAMMING TOOLS**

**POWERFUL  
3D SIMULATOR**

**PROFESSIONAL  
LEARNING**

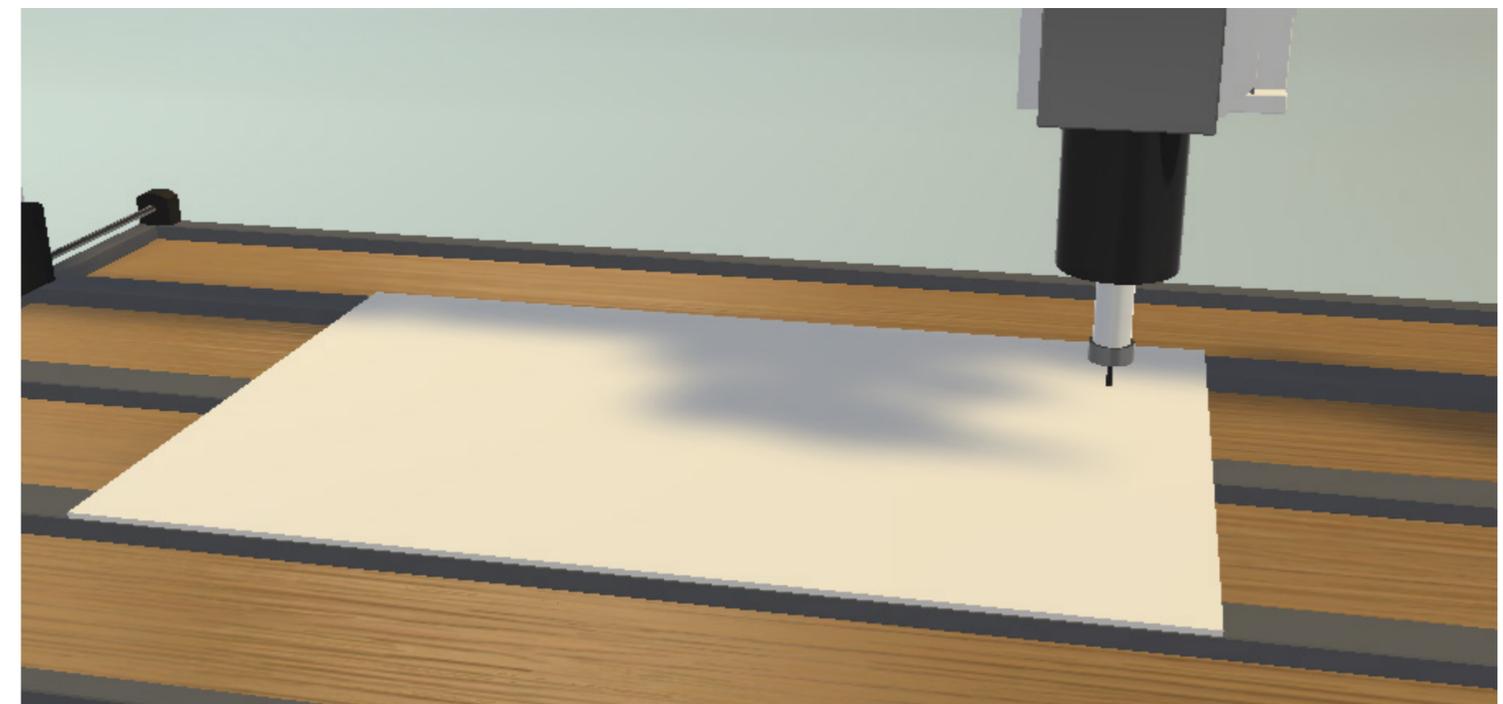
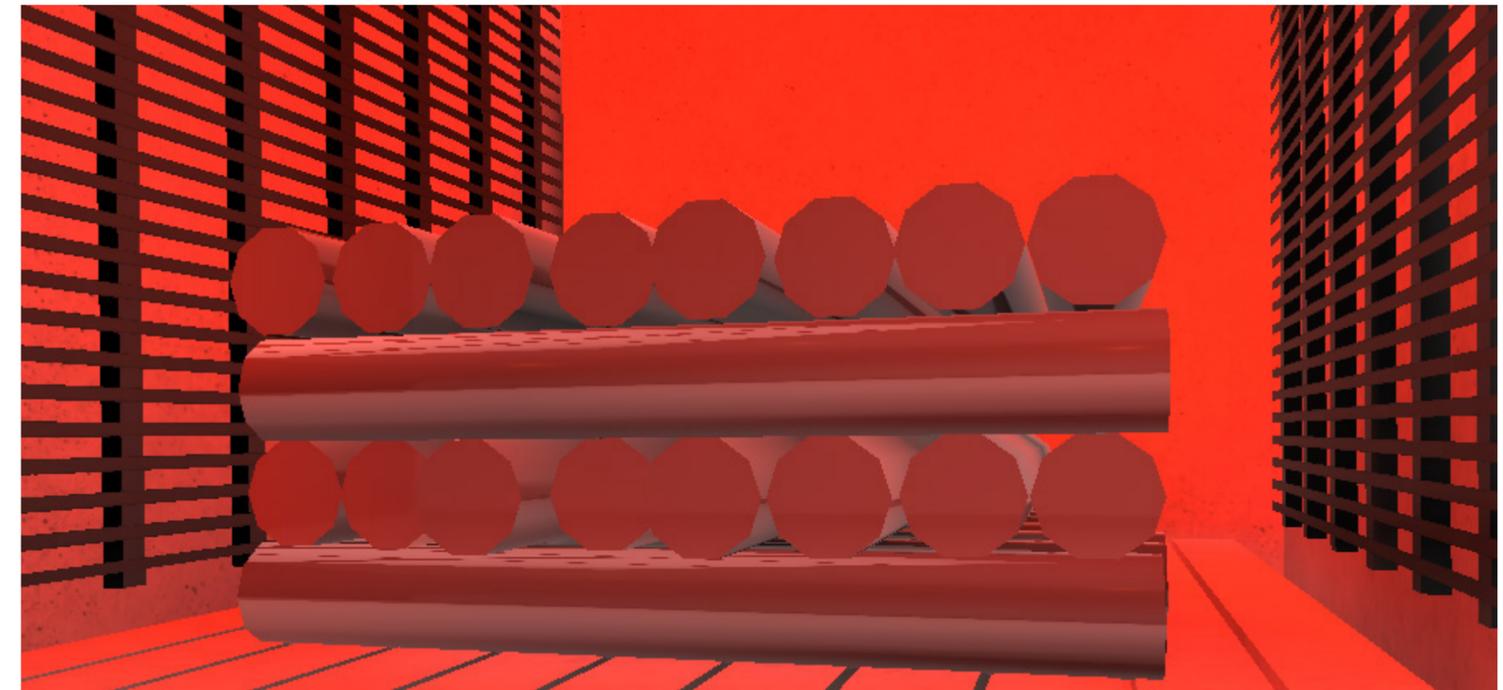
**INDUSTRIAL REALISTIC  
ENVIRONMENTS**



**PROFESSIONAL EXPERIENCE**

**REAL-LIFE SITUATIONS**

# 3D INDUSTRIAL ENVIRONMENTS TO PROVIDE REAL PRACTICAL EXPERIENCE TO STUDENTS



# EFFECTIVE LEARNING WITH GUIDANCE, REAL-LIFE PROJECTS, THEORY AND INSTRUCTIONS FROM BASIC TO ADVANCED

## 1 STUDYING THE PLANT HEATING FURNACE

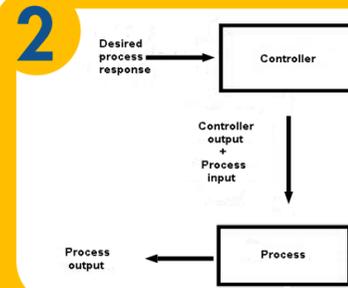
**ABOUT THIS TASK**  
In this course we will work with 3 plants. Initially we will study our control platform and this the dynamic behavior of this first plant: the heating furnace.

**STUDY AND LEARN**  
Before we start working with the practical part of the course, it is important that you read the content below to know some important control concepts. From now on we will use these concepts a lot to deal with how to control each system

### STUDYING AND EXPERIMENTING THE SYSTEMS

**Goal:** Familiarize the student with basic control concepts and introduce him/her to plants.

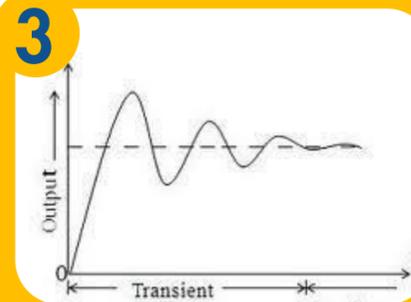
**Control contents:** Studying the plant, control concepts, first steps, communication.



### OPEN-LOOP CONTROL

**Goal:** Implement and discuss a system controlled by the user.

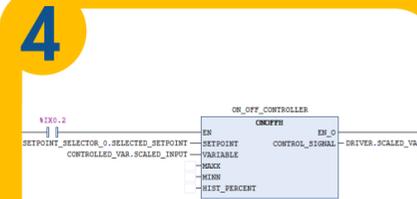
**Control contents:** Open loop control.



### TRANSIENT AND STEADY-STATE RESPONSE

**Goal:** Study the 2 parts of a response and their importance.

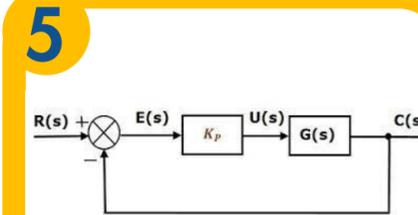
**Control contents:** System response.



### ON-OFF CONTROL

**Goal:** Implement an on-off controller and evaluate its performance.

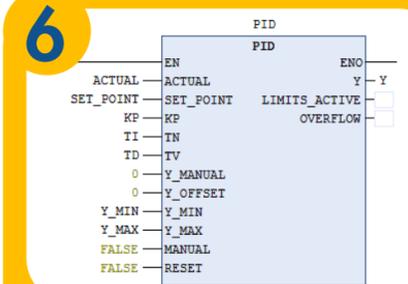
**Control contents:** On-off controller.



### PROPORTIONAL CONTROL

**Goal:** Implement a proportional controller and discuss its advantages and limitations.

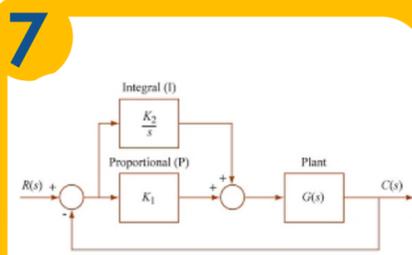
**Control contents:** Proportional controller.



### CODESYS PID BLOCK

**Goal:** Present the Siemens PID controller to be used as a tool from this point on.

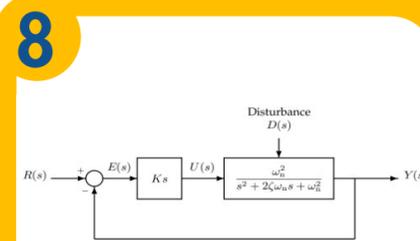
**Control contents:** PID controller.



### PI CONTROLLER

**Goal:** Implement a PI controller, present how to tune it, and study the impact of the integral action.

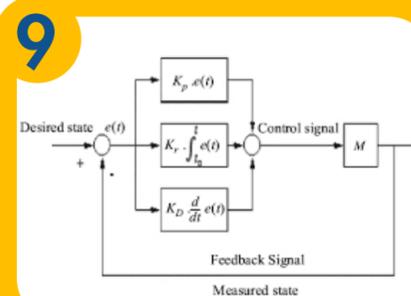
**Control contents:** PI controller.



### PD CONTROLLER

**Goal:** Implement a PD controller and study the derivative contribution.

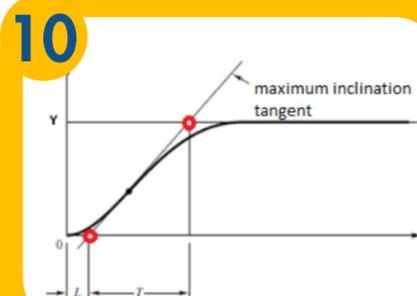
**Control contents:** PD controller.



### PID CONTROLLER

**Goal:** Implement a PID controller and study its performance.

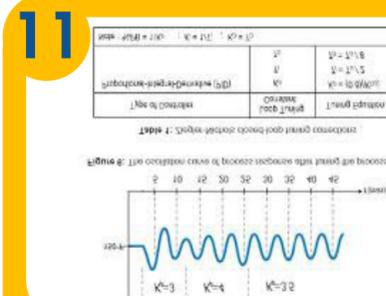
**Control contents:** PID controller.



### ZIEGLER-NICHOLS METHOD (OPEN LOOP)

**Goal:** Present and apply the Ziegler-Nichols method to a control system.

**Control contents:** Ziegler-Nichols (open loop).



### ZIEGLER-NICHOLS METHOD (CLOSED LOOP)

**Goal:** Present and apply the Ziegler-Nichols method to a control system.

**Control contents:** Ziegler-Nichols (closed loop).

TYREUS AND LUYVEN CLOSED-LOOP METHOD

Below is the table with the parameter values suggested by the method

Controller	$K_p$	$T_i$	$T_d$
PI	$K_{cr}/3.2$	$2.2P_{cr}$	0
PID	$K_{cr}/2.2$	$2.2P_{cr}$	$P_{cr}/6.3$

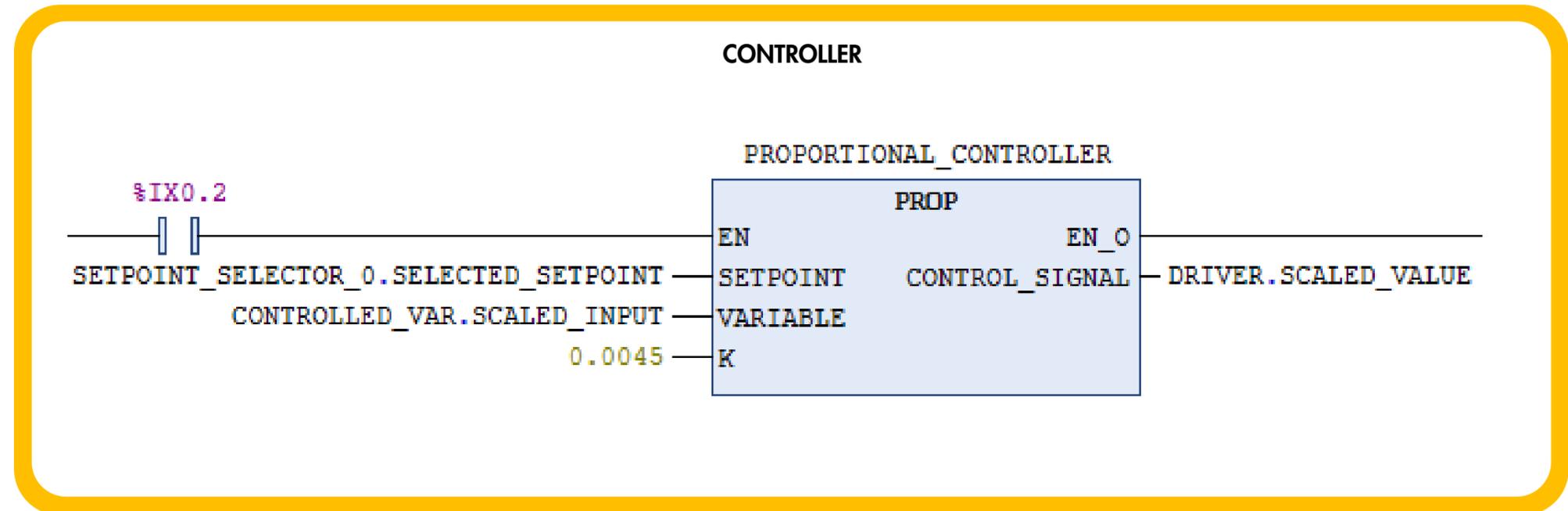
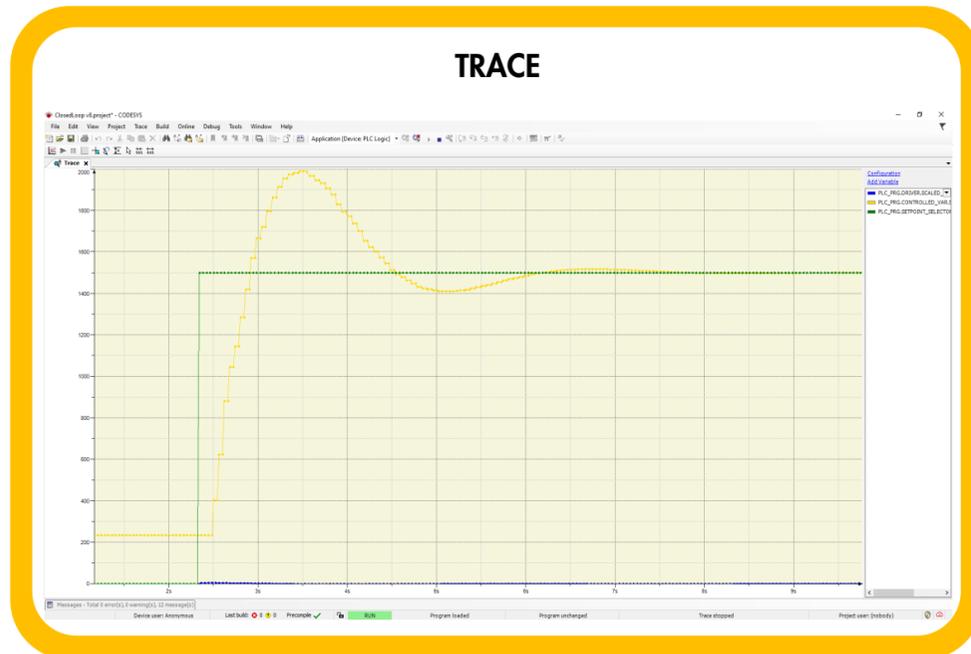
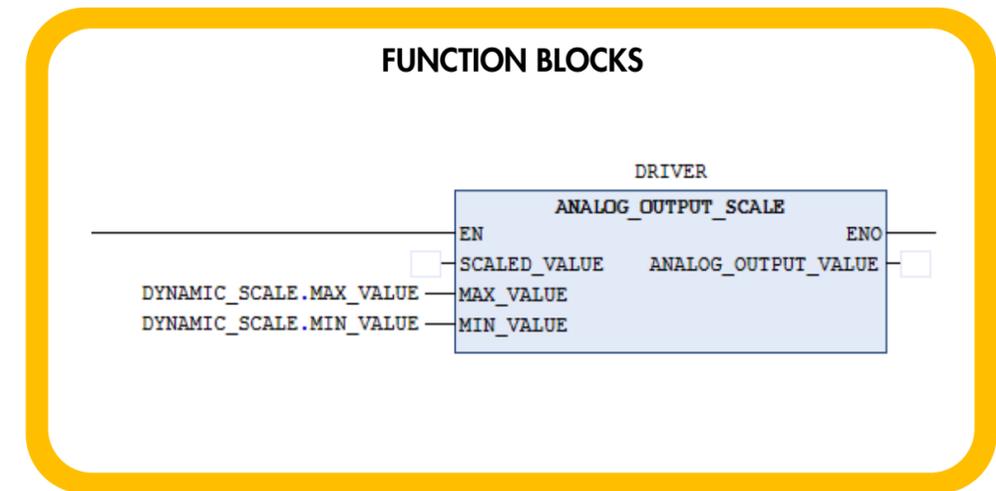
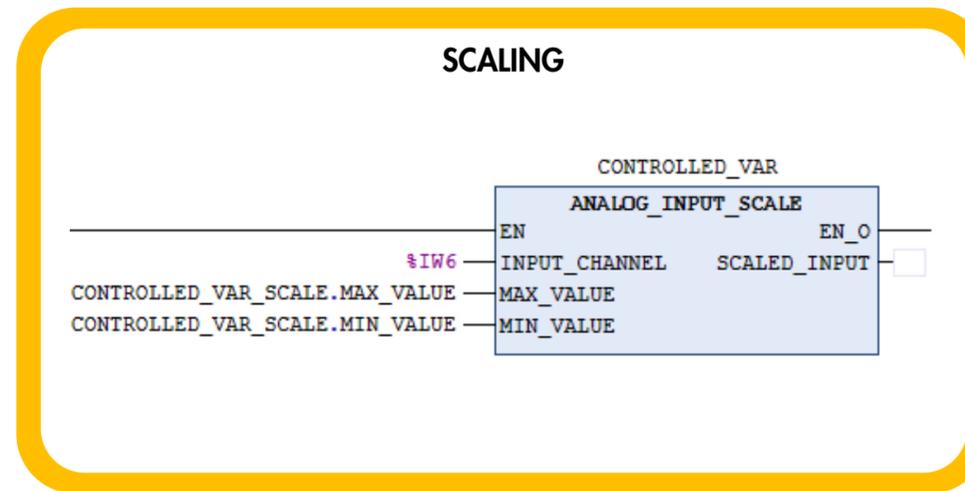
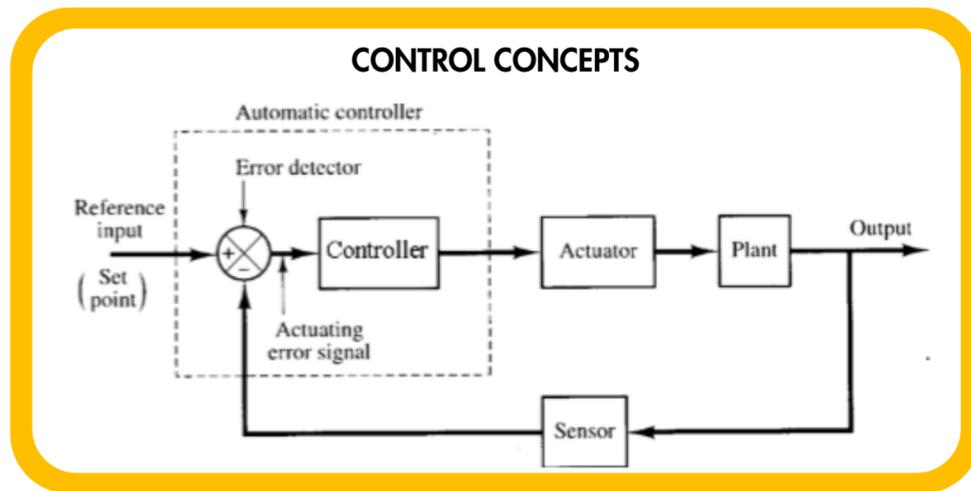
### OTHER PARAMETRIZATION METHODS

**Goal:** Study and implement other parametrization methods.

**Control contents:** Other parametrization methods.

# STUDENT CAN LEARN AND PRACTICE FROM BASIC TO ADVANCED CONTROL TOPICS

With the industrial 3D environments and also the built-in projects it's possible to develop solutions that evolve basic control approaches, like open loop control, controllers tuning (ON-OFF, P, PI, PD, PID) and some tuning methods, like Ziegler-Nichols closed loop method.





# SUMMARY OF FEATURES

## IT'S A 3D SIMULATOR



## IT HAS BUILT-IN PROJECTS

### PLANT 1 - HEATING FURNACE

It's a heating furnace for materials with heating capacity up to 1000 degrees. Thermal systems exist in almost all industries. In our plant the heating takes place by Joule effect. A resistance bank is controlled by a power drive that receives an analog signal from 0 to 10VDC. The temperature of the sensor goes from 0 to 1000 degrees. The cooling is obtained by natural means. By nature it is a slow plant. In our virtual plant it will be faster than normal, because otherwise you would take hours to do a task.

For this task you must have Codesys installed on your

## THE PROJECTS INCLUDE GUIDANCE

### TASK SPECIFICATION

With the furnace plant open at the VFA wait for the LED indicating communication with the PLCsim turn green and:

1. Activate the buttons of the two selector bits (0 and 1);
2. Move the potentiometer and check the effect of the control signal that you are producing in the controlled quantity;
3. Confirm the minimum and maximum values of the control signal obtained at the ends of the potentiometer;
4. Confirm the minimum and maximum values of the controlled magnitude;

+ CONTENTS AND SUPPORT MATERIALS, SO THEY CAN LEARN BY THEMSELVES

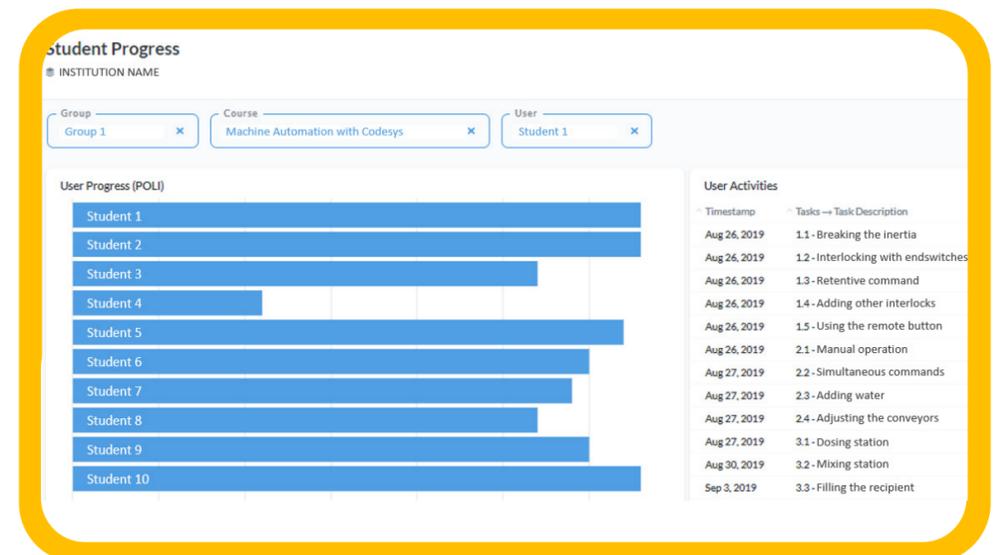
### Control contents:

- Control concepts
- Open vs closed loop
- Excitations in a Plant
- Transient and steady state response
- ON-OFF control

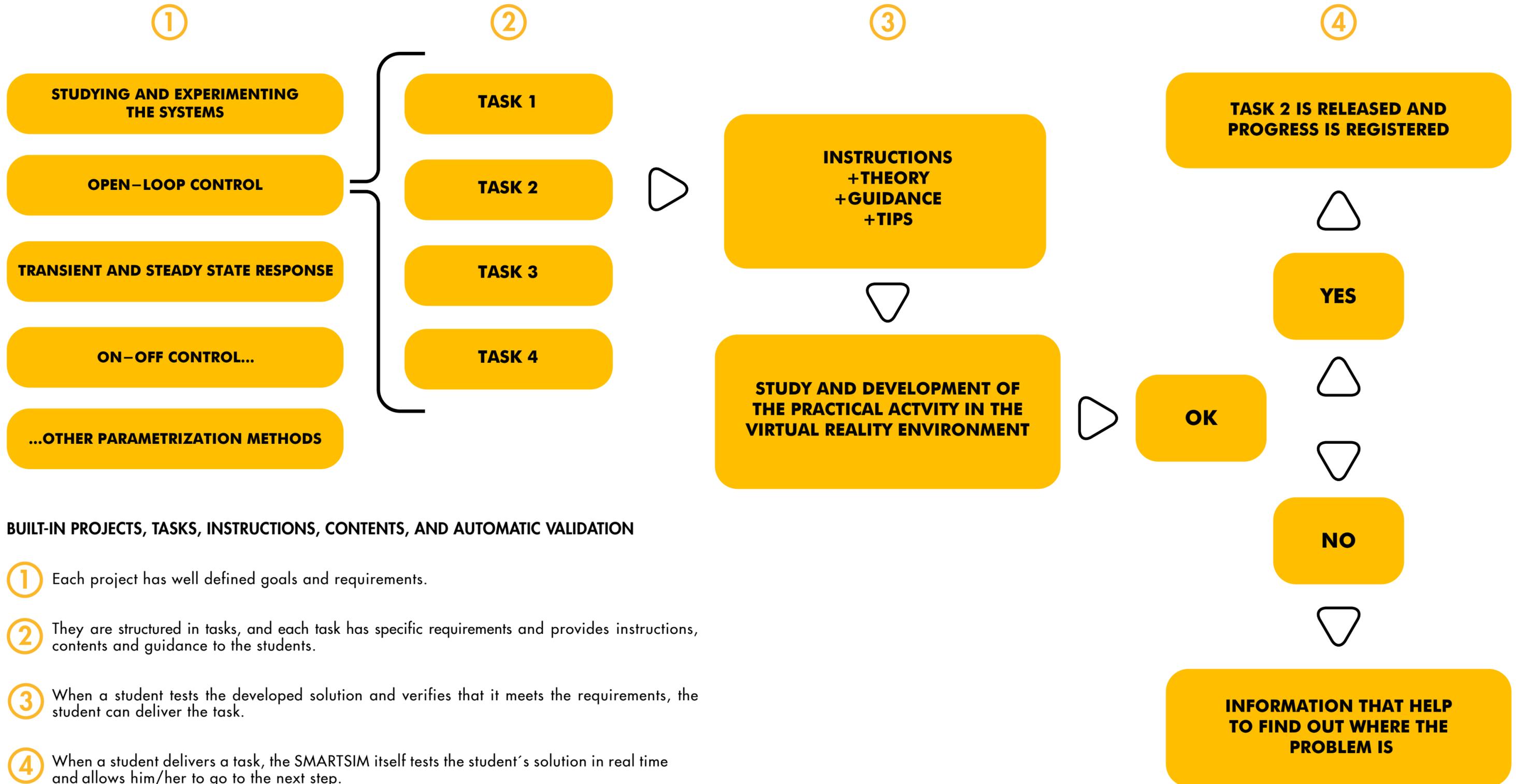
IT AUTOMATICALLY CHECKS STUDENT ACTIVITIES TO LET THEM MOVE ON, LIKE IN GAME



PROFESSORS CAN MONITOR STUDENTS, AND VERIFY WHICH POINT THEY NEED HELP (Option available with Dashboard)



# HOW ARE BUILT-IN PROJECTS STRUCTURED?



## BUILT-IN PROJECTS, TASKS, INSTRUCTIONS, CONTENTS, AND AUTOMATIC VALIDATION

- ① Each project has well defined goals and requirements.
- ② They are structured in tasks, and each task has specific requirements and provides instructions, contents and guidance to the students.
- ③ When a student tests the developed solution and verifies that it meets the requirements, the student can deliver the task.
- ④ When a student delivers a task, the SMARTSIM itself tests the student's solution in real time and allows him/her to go to the next step.

# SYSTEM REQUIREMENTS

## ORDER CODES

### DL SMART-DCSC

DYNAMIC CONTROL SYSTEMS COURSE FOR CODESYS

### DL SMART-DCST

DYNAMIC CONTROL SYSTEMS COURSE FOR TIA PORTAL

### DL SMART-DASHBOARD

CLASSROOM MANAGEMENT DASHBOARD FOR SMARTSIMS

### IMPORTANT NOTE:

THIS PRODUCTS DO NOT INCLUDE ANY THIRD PARTY SOFTWARES SUCH AS TIA PORTAL, PLCSIM, CODESYS OR CODESYS CONTROLWIN.

TO OUR KNOWLEDGE, CODESYS DEVELOPMENT SYSTEM CAN BE DOWNLOADED FOR FREE AT CODESYS STORE.

TIA PORTAL STEP7 + PLCSIM HAVE TRIAL VERSIONS ON SIEMENS WEBSITE. AND AN EDUCATIONAL VERSION CAN BE PURCHASED BY SIEMENS.

## MINIMUM REQUIREMENTS

### OPERATIONAL SYSTEM

64-BIT WINDOWS 10

### DIRECTX VERSION

DIRECTX 11

### PROCESSOR

INTEL i5 9400F OR AMD RYZEN 5 3600

### MEMORY

8GB

### GRAPHIC CARD

### STORAGE

HDD (1GB)

## RECOMMENDED REQUIREMENTS

### OPERATIONAL SYSTEM

64-BIT WINDOWS 10 PRO

### DIRECTX VERSION

DIRECTX 12

### PROCESSOR

INTEL i7 9700 OR AMD RYZEN 7 3700X

### MEMORY

16 GB

### GRAPHIC CARD

NVIDIA GTX 1050 TI 4GB OR RX 550 4GB

### STORAGE

HDD (1GB)